# Integration of Frequency Dependent Soil Electrical Properties in Grounding Electrode Circuit Model

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Article Info	ABSTRACT			
Article history:	The effect of frequency dependent soil properties on the impedance and			
Received Oct 9, 2015 Revised Dec 11, 2015 Accepted Jan 3, 2016	transient response of the grounding electrode was investigated. The frequency dependent soil models as proposed by Scott, Smith-Longmire, and Visacro-Alipio were critically reviewed. A novel method was proposed to integrate the frequency dependent soil electrical properties in the circuit model of grounding electrode. To validate the application of the method in circuit model, the voltage responses of the grounding electrode obtained by the circuitand electromagnetic models were compared. The voltage responses obtained by the circuit and electromagnetic models were in excellent agreement in terms of voltage peaks and wave shapes. The differences			
<i>Keyword:</i> Circuit model Electromagnetic model				
Frequency dependent Grounding electrode Soil electrical properties	were found less than 1%. Copyright © 2016 Institute of Advanced Engineering and Scient			
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# 1. INTRODUCTION

Transient currents caused by faults and lightning strikes have significant effects on power system performance [1, 2]. Thw high amplitude currents are dispersed into the earth through the grounding electrodes embedded inside the soil [3]. The performance of grounding electrodes is dependent on the soil electrical properties, electrode dimensions, and current parameters [4-7]. The soil conductivity and permittivity are influenced by several parameters such as soil compaction, temperature, moisture, and grain size [8]. In addition, they are also influenced by the frequency of the current. The higher the frequency, the lower the soil conductivity and permittivity [9, 10]. As a result, the transient impedance of the electrode is also affected [11-14]. Despite all the above, the effect of frequency on soil electrical properties is usually disregarded in high frequency grounding system analyses. For instance, in CDEGS software (Current Distribution, Electromagnetic Fields, Grounding and Soil Structure Analysis program provided by the Safe Engineering Services and Technologies Ltd., Québec, Canada), the measured soil conductivity and soil permittivity are used in the computation, even though the conductivity and permittivity are usually measured by using either DC or low frequency sources. In addition, in circuit approach, the application of the frequency dependent soil properties in impulse condition is neglected. This is because applying each individual frequency of lightning current is difficult.

In this paper, the frequency dependent soil models as proposed by Scott [9], Smith-Longmire [15], and Visacro-Alipio [16] are critically reviewed. In addition, the simultaneous effect of frequency on both soil conductivity and permittivity, and hence on the grounding electrode impedance is discussed. A novel method is proposed to incorporate the frequency dependent soil electrical properties in circuit model of grounding electrode. The difference between the voltage responses obtained by the proposed method in the circuit

model and obtained by the electromagnetic with the method of moment (EM-MoM) under first and subsequent return stroke currents was found less than 1%.

The result shows that the influence of frequency on the grounding impedance and its transient performance must be taken into account when carrying out a grounding system transient analysis.

# 2. FREQUENCY DEPENDENT SOIL MODELS

Several models have been proposed to determine the soil electrical properties as a function of frequency [9, 15, 16]. In this section, the models proposed by Scott [9], Smith-Longmire [15], and Visacro-Alipio [16] are described. In this study, the frequency dependent soil electrical parameters obtained by these models had been compared with the experimental values.

#### 2.1. Scott Model

The frequency dependent conductivity,  $\sigma(f)$ , and frequency dependent relative permittivity,  $\varepsilon(f)$ , were determined using the formulas proposed by Scott [9] as

$$\sigma(f) = 0.028 + 1.098\sigma_0 - 0.068f + 0.036\sigma_0^2 - 0.046f\sigma_0 + 0.018f^2$$
(1)

$$\varepsilon_r(f) = 5.491 + 0.946 \,\sigma_0 - 1.097 \,f + 0.069 \,\sigma_0^2 - 0.114 \,f\sigma_0 + 0.067 \,f^2 \tag{2}$$

where  $\sigma_0$  is the nominal low frequency soil conductivity, and *f* is the applied frequency in the range of 100Hz to 1MHz.

#### 2.2. Smith-Longmire Model

The Smith and Longmire expressions were used to compute the soil relative permittivity and soil conductivity values. The frequency-dependent soil relative permittivity and conductivity are

$$\varepsilon_r(f) = \varepsilon_\infty + \sum_{i=1}^{18} \frac{a_i}{1 + \left(\frac{f}{F_i}\right)^2} \tag{3}$$

$$\sigma(f) = \sigma_{DC} + 2\pi\varepsilon_0 \sum_{i=1}^{18} a_i F_i \frac{\left(\frac{f}{F_i}\right)^2}{1 + \left(\frac{f}{F_i}\right)^2}$$
(4)

where  $\sigma_{DC}$  is dc soil conductivity,  $\varepsilon_{\infty}$  is high frequency limit of the dielectric constant, which was set to 5. The value of coefficient  $a_i$  was referred from Table 1. The parameters  $F_i$  is obtained using

$$F_i = F(\sigma_{DC}) 10^{i-1} \tag{5}$$

Where

$$F(\sigma_{DC}) = (125\sigma_{DC})^{0.8312}$$
(6)

Tab	le 1.	Coefficient $a_i$	
			_

i	$a_i$	i	$a_i$
1	$3.40 \times 10^{6}$	8	$1.25 \times 10^{1}$
2	$2.74 \times 10^{5}$	9	$4.80 \times 10^{0}$
3	$2.58 \times 10^{4}$	10	$2.17 \times 10^{0}$
4	$3.38 \times 10^{3}$	11	9.80×10 <sup>-1</sup>
5	$5.26 \times 10^{2}$	12	3.92×10 <sup>-1</sup>
6	$1.33 \times 10^{2}$	13	1.73×10 <sup>-1</sup>
7	$2.72 \times 10^{1}$		

#### 2.3. Visacro-Alipio Model

The Visacro-Alipio expressions were obtained according to large number of field measurements. The frequency dependent relative permittivity and conductivity of soil were obtained using

$$\varepsilon_r(f) = 7.6 \times 10^3 f^{-0.4} + 1.3 \tag{7}$$

$$\sigma(f) = \sigma_0 \left[ 1 + \left( 1.2 \times 10^{-6} \left( \frac{1}{\sigma_0} \right)^{0.73} \right) (f - 100)^{0.65} \right]$$
(8)

where  $\sigma_0$  is nominal low frequency soil conductivity, and *f* is applied frequency in the range of 100Hz to 4MHz.

#### 2.4. Comparison of the Soil Models

The frequency dependent soil properties obtained by Scott, Smith-Longmire, and Visacro-Alipio formulas were then compared with the experimental value to evaluate the accuracy of the soil models. Comparisons of the frequency dependent soil properties for low frequency soil resistivity values of 93.2  $\Omega$ .m, and 343 $\Omega$ .m are shown in Figures 1 and 2. As seen in both figures, all soil models were able to predict the frequency dependent soil resistivity values in different frequencies compared to the experimental values. However, in term of predicting the relative permittivity values, the Visacro-Alipio's soil model was found unable to properly predict the frequency dependent relative permittivity values.



Figure 1. Frequency dependent soil electrical properties for  $\rho_0$ =93.2  $\Omega$ .m obtained by different soil models



Figure 2. Frequency dependent soil electrical properties for  $\rho_0=343 \ \Omega$ .m obtained by different soil models

Integration of Frequency Dependent Soil Electrical Properties in Grounding Electrode ... (Zulkurnain A.M.)

# 3. HARMONIC GROUNDING ELECTRODE IMPEDANCE CHARACTERISTIC

This section discusses the effect of frequency on harmonic grounding electrode impedance under first and subsequent return stroke currents. A horizontal copper electrode with 10-m length and 5-mm radius was assumed located at 1-m depth in a uniform soil. Three different types of soil with low resistivity value ( $\rho$ =100  $\Omega$ .m), and high resistivity value ( $\rho$ =1000  $\Omega$ .m) were considered.

The first return stroke current had a peak value of 30 kA, maximum steepness of 12 kA/ $\mu$ s, and zero to peak time of 8  $\mu$ s. The subsequent return stroke current had a peak value of 12 kA, a maximum steepness of 40 kA/ $\mu$ s, and zero to peak time of 0.8  $\mu$ s. The two waveforms were represented using Heidler's function [17], the parameters of which are given in [18].

The impedance characteristic of the electrodes according to the different soil models under first and subsequent return stroke currents are shown in Figures 3 and 4. The harmonic impedance was obtained as the ratio of grounding electrode voltage, and current as  $Z(\omega)=V(\omega)/I(\omega)$ . As seen in both figures, the harmonic impedance characteristics obtained by Scott and Smith-Longmire models were in accordance. The harmonic impedances obtained by Visacro-Alipio's model had large difference compared to the harmonic impedances obtained by Scott and Smith-Longmire models.



Figure 3. Impedance characteristics of the grounding electrode  $\rho_0=100 \ \Omega.m$ 



Figure 4. Impedance characteristics of the grounding electrode  $\rho_0$ =1000  $\Omega$ .m

# 4. TIME DOMAIN VOLTAGE RESPONSE OF THE ELECTRODE

This section discusses the determination of the voltage response of the electrode with respect to the frequency dependent soil properties through computation. A novel method was applied to integrate the frequency dependent soil properties in circuit approach. This method improved the voltage response of the electrode with respect to the frequency dependent soil properties.

# 4.1. Electromagnetic Model with the Method of Moment

The electromagnetic model with the method of moment is known as the most accurate model to analyze the grounding electrode. The methodology used in the electromagnetic model in disscussed. However, more details can be found in [19]. In electromagnetic approach with the method of moment (EM-MoM), the injected current is specified as an impulse signal. Fast Fourier transform (FFT) was used to decompose the time domain current i(t) into its corresponding frequency spectrum  $i(\omega)$ . The discrete frequency spectrum of the input current was in a range from the lowest frequency to the highest frequency (Nyquist frequency). First, the electrode was discretized into N equal conductor segments. The current in each segment was then determined by applying MoM to enforce the continuity of the tangential component of the electric field along the segments. Once the current in each conductorsegment was known, the electric field (*E*) caused by the currents at all computation points in the soil could be obtained. Consequently, other electromagnetic field values and derived quantities, such as electrode voltage, could also be obtained. To obtain the voltage in time domain, fast inverse Fourier transform (IFFT) was applied.

## 4.2. Circuit Model

A grounding electrode can be presented as an equivalent lumped circuit model [20, 21]. The model contains R, L, and C elements. Since the soil ionization factor was not taken into account in this study due to the application of low amplitude current, Rudenberg circuit model, as illustrated in Figure 5 [20], was used to model the grounding electrode. The R-L-C elements were set as the grounding resistance R in  $\Omega$  (or alternatively, the conductance G in S), the electrode inductance L in  $\mu$ H, and the soil capacitance C in F. Note that under fast-fronted currents, the proposed method in [21] was taken into account to determine the electrode inductance. For a horizontal grounding electrode in a uniform soil, the circuit elements could be obtained using the formulas initially proposed by Sunde [22]:

$$R = \frac{1}{G} = \frac{\rho}{\pi l} \left[ \ln(\frac{2l}{\sqrt{2ad}}) - 1 \right]$$
(9)

$$L = \frac{\mu l}{2\pi} [\ln(\frac{2l}{a}) - 1]$$
(10)

$$C = \frac{\rho\varepsilon}{R} \tag{11}$$

where  $\rho$  is soil resistivity in [ $\Omega$ .m], l is length of the electrode in [m], a is radius of the electrode in [m], d is burial depth in [m],  $\mu$  is soil permeability ( $4\pi \times 10-7$ H/m), and  $\varepsilon$  is permittivity of soil in [F/m]. Obviously, the important material properties seen in (9) to (11) are  $\rho$ ,  $\mu$ , and  $\varepsilon$  for the resistance, inductance, and capacitance, respectively. However, only the resistivity and permittivity are frequency dependent, and hence only these two parameters were considered in this work.



Figure 5. Representation of a typical grounding electrode by an equivalent lumped circuit model

It is known that the circuit approach is a simple approach compared to the electromagnetic approach to analyze the transient behavior of the grounding electrode. However, the difficulty of incorporating the frequency dependent soil properties limits the application of the approach in transient analysis, since the lightning current has frequency components. To investigate the effect of lightning current's front time,  $T_{f_2}$ , on the resistivity and permittivity, the equivalent frequency,  $f_{eq}$ , of the lightning current [23, 24]was determined using

$$f_{eq} = \frac{1}{4T_f} \tag{12}$$

Integration of Frequency Dependent Soil Electrical Properties in Grounding Electrode ... (Zulkurnain A.M.)

 $f_{eq}$  was then used in frequency dependent soil properties soil models. Finally, the circuit element values of the electrode model as shown in Figure 5 with the frequency dependent soil properties were obtained.

#### 5. VALIDATION OF THE METHOD

For validation, the voltage responses obtained by the circuit model and EM-MoMwere compared. In this comparison, the typical electrode and lightning currents defined in Section 2 were taken into account. The equivalent frequencies for the first and subsequent return stroke currents were  $f_{eq}$ =31.25 kHz and  $f_{eq}$ =312.5 kHz, respectively. Scott soil model was taken into account to determine the frequency dependent soil properties. The voltage responses obtained by the circuit and EM-MoMwere in excellent agreement in terms of both peak values and waveforms as shown in Figures 6 and 7. The differences between voltage peaks obtained by the circuit model and EM-MoM for the first and subsequent return stroke currents when  $\rho_0$ =100  $\Omega$ .m were 0.5% and 0.5%, respectively. In addition, the differences between voltage peaks obtained by the circuit model and EM-MoM for the first and subsequent return stroke currents when  $\rho_0$ =1000  $\Omega$ .m were 0.9% and 1%, respectively. These differences prove that integrating the frequency dependent soil properties in the application of equivalent frequency in circuit model is an appropriate method in circuit approach.



Figure 6. Voltage responses obtained by the circuit and EM-MoM for  $\rho_0=100 \ \Omega$ .m



Figure 7. Voltage responses obtained by the circuit and EM-MoM for  $\rho_0=1000 \ \Omega$ .m

## 6. CONCLUSION

The frequency dependent soil models have been reviewed. The accuracy of the models has been investigated by comparing the results obtained by the models and experimental values. The comparison among the models and experimental values show that Scott and Smith-Longmire models are more accurate

compared to the Visacro-Alipio's model. The effect of the frequency dependent soil electrical properties on grounding electrode impedance has been investigated by using the frequency dependent soil models. It is found that the impedance of the typical grounding electrode buried in soil changes as a function of frequency. The characteristic of the grounding electrode is found dependent on the soil resistivity. The characteristics of the grounding electrode is proposed to improve the voltage response of the electrode obtained by the circuit model of the grounding electrode. The application of the method in circuit model shows that the voltage responses obtained by the proposed method and electromagnetic model are in excellent agreement in terms of peak value and wave shape. The differences between the voltage peaks obtained by the proposed method and electromagnetic model are found less than 1%. This finding shows that an overall improvement of grounding electrode performance can be achieved by applying the proposed method into the circuit models of the grounding electrode swhen carrying out transient grounding analyses.

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